YKAN

Absolute Encoder Series KEA-58KS

Operation Manual

Thank you for purchasing this series KEA-58KS Absolute Encoders. Please read this Operation Manual carefully before applying this product.

PLEASE KEEP MANUAL IN A SAFE PLACE!

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JELWX-M8586B-E

Safety Consideration

This indicates contents which can cause large accidents Warning leading to loss of life or severe injury when the indication is disregarded and wrong handling is executed.

This indicates contents which can cause injury or **Caution** material damage when the indication is disregarded and wrong handling is executed.

Explanation of the pictograms

This symbol indicates a general prohibition.

This symbol indicates a compulsory item or an instruction.

[Operating environment and conditions]

∕!**∖Warnin**g

Do not use in a combustible or explosive atmosphere. Otherwise personal injury or fire may be caused.

Do not use this product for applications related to human safety. Use is assumed in an application where an accident or incorrect use will not immediately cause danger to humans.

[Operating environment and conditions]

Caution

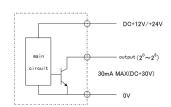
- Use and store the equipment within the scope of the environment (vibrations, impact, temperature, humidity etc.) specified in the
 - Otherwise fire or product damage may be caused.
- Understand the product first before use it.

[Installation and wiring]

∕!**∖Warning**

- Use only with the power supply voltage listed in the specifications. Otherwise fire, electric shock, or accidents may be caused.
- Use only with the wiring and layout specified in the specifications. Otherwise fire, electric shock, or accidents may be caused.
- Do not apply any kind of stress to the wires. Otherwise electric shock or fire may be caused.

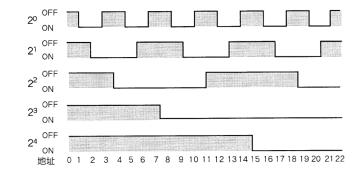
Output circuit



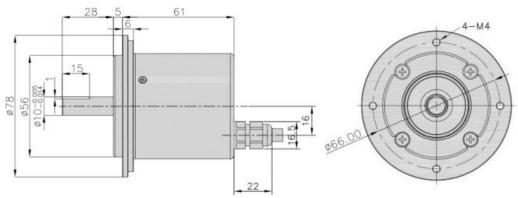
Connection

Pin	Color of	Resolution	
number	cable	360	
1	Brown	DC+12/24V	
2	Blue	0V	
3	Black	No connect	
4	Red	Bit1 (2 ⁰)	
5	Orange	Bit2 (2 ¹)	
6	Yellow	Bit3 (2 ²)	
7	Green	Bit4 (2 ³)	
8	Purple	Bit5 (2 ⁴)	
9	Gray	Bit6 (2 ⁵)	
10	White	Bit7 (2 ⁶)	
11	Black/White	Bit8 (2 ⁷)	
12	Red/White	Bit9 (2 ⁸)	
Shield		GND	

Output Waveform



External dimensions (Unit: mm)



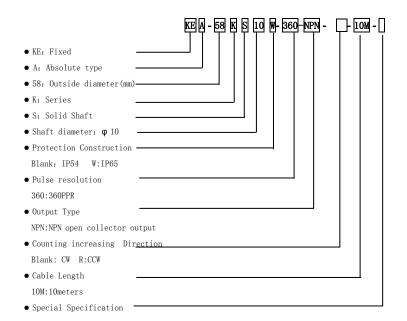
■ Mechanical specifications

Starting	torque	Max. 0.04N • m (+20℃)			
Shaft momen	nt of inertia	5.7×10 ⁻⁶ kg • m ²			
Max. allowable	Radial	100N			
shaft load	Thrust	50N			
Max. allowa	ible speed	5000rpm			
	Material	Oil-resistant PVC(with shielded cable)			
0-1-1-	Nominal core cross section	About 0.14mm ² (AWG26)			
Cable	External diameter	Approx. 7.0mm(12pin)			
	length	10m(standard)			
Wei	ght	Approx.1100g(cable length 10m)			

Environmental requirements

Operation temperature: −10~+50°C
Storage temperature: −25~+80°C
35~85%RH (non-condensing)
AC500V (50/60Hz) 1minute
10MΩ min.
Durable for 1h along 3 axes at 10 to 55Hz with 0.75mm amplitudes
11ms with 490m/s ² applied 3 times 3 axes
IP65(Dustproof and water jet-proof type

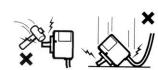
Composition of model number



Electrical specifications

	Type No.	KEA-58KS10W-360-NPN-10M
Power supply	Operating voltage	DC+10.8V~26.4V DC
	Allowable ripple	3%rms Max.
	Current consumption	50mA Max. (without load)
Output waveform	Signal format	Binary gray code
	Max. response frequency	20KHz
	Electric Max. allowable speed	(Maximum response frequency/Pulse)x60 (The encoder can not respond to revolution faster than the electric maximum allowable speed.)
	Precision	[360/ (resolutionx2]°
	Direction	Output code increments in positive direction of CW, Output code decrements in negative direction of CCW (CW means clockwise revolution viewed from the shaft.)
Output	Rising/falling time	$2\mu s$ Max.(Load Resistance less than $1k\Omega$) (with 10m cable)
	Rising/falling time	$2\mu s$ Max.(Load Resistance less than $1k\Omega$) (with 10m cable)
	Output type	open collector output(NPN)
	Output logic	Negative logic (low active)
	Residual voltage	0.4V Max.
	Inflow current	30mA Max.
	Load power supply voltage	DC30V Max.

Cautions for use



- Do not wire the cable in parallel with other power lines and do not share a duct with other cables.
- Use capacitors or surge absorption elements to remove the sparks caused by relays and switches in the control panel as far as possible.
- Be sure to connect all wires properly, as wrong wiring can damage the internal circuitry.
- Use a specified coupling for connecting the encoder shaft and the shaft of a machine to be controlled. Do not squeeze the shaft into the coupling.
- The service life of the bearing is largely affected by the amount of load to the shaft. Try to reduce the load as much as possible.
- Do not disassemble the product.
- As the rotary encoder is composed of precision parts, its function will be impaired when it is subjected to shocks. Use sufficient care for handling and mounting.